

Optimization of lowest Robin eigenvalues on 2-manifolds and unbounded cones

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Trending Topics in Spectral Theory, Marseille, 3.12.2019

- 1 Motivation & background
- 2 Optimization on 2-manifolds
- 3 Optimization on unbounded cones
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Purely discrete spectrum

$$\lambda_1^\beta(\Omega) \leq \lambda_2^\beta(\Omega) \leq \dots \leq \lambda_k^\beta(\Omega) \leq \dots \quad (\beta \cdot \lambda_1^\beta(\Omega) \geq 0)$$

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The ball (the disk) is:

- ① minimizer ($\beta > 0$, $|\Omega| = \text{const}$)
Bossel-86, Daners-06
- ② maximizer ($\beta < 0$, $|\partial\Omega| = \text{const}$, $d=2$),
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1st main objective

To generalize (2) for 2-manifolds.

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$$H_{\beta, \Lambda_m} \simeq \beta^2 H_{-1, \Lambda_m} \quad \Longrightarrow \quad H_{\Lambda_m} := H_{-1, \Lambda_m}.$$

Spectral properties of H_{Λ_m}

Proposition (Pankrashkin-16)

- $\sigma_{\text{ess}}(H_{\Lambda_m}) = [-1, \infty)$.
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2nd main objective

To obtain an isoperimetric inequality for $\lambda_1(\Lambda_m)$.

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Distance functions ($x, y \in \mathcal{M}$)

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$R_{\mathcal{M}} := \max_{x \in \mathcal{M}} \rho_{\partial\mathcal{M}}(x)$ (the in-radius of \mathcal{M})

Definition of the operator

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$K \equiv 0$ corresponds to the flat case.

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$\mathcal{B}^o \subset \mathcal{N}_o$ – a geodesic disk.

$$\mathcal{N}_o \simeq \begin{cases} \mathbb{R}^2, & K_o = 0, \\ S^2_{\frac{1}{\sqrt{K_o}}}, & K_o > 0. \end{cases}$$

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Theorem (Khalile-L-19)

$$\begin{cases} |\partial \mathcal{M}| = |\partial \mathcal{B}^\circ| \\ K_o \cdot \max\{|\mathcal{M}|, |\mathcal{B}^\circ|\} \leq 2\pi \end{cases} \implies \lambda_1^\beta(\mathcal{M}) \leq \lambda_1^\beta(\mathcal{B}^\circ), \quad \forall \beta < 0.$$

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Counterexample on \mathbb{S}^2 ($K_0 = 1$): $\mathcal{B}^\circ \subset \mathbb{S}^2$, $|\mathcal{B}^\circ| < 2\pi$, $\mathcal{M} := \mathbb{S}^2 \setminus \mathcal{B}^\circ$

Weak coupling expansions $\beta \rightarrow 0$

$$\lambda_1^\beta(\mathcal{M}) \sim \frac{\beta|\partial\mathcal{B}^\circ|}{4\pi - |\mathcal{B}^\circ|} \quad \text{and} \quad \lambda_1^\beta(\mathcal{B}^\circ) \sim \frac{\beta|\partial\mathcal{B}^\circ|}{|\mathcal{B}^\circ|}.$$

Hence, $\lambda_1^\beta(\mathcal{M}) > \lambda_1^\beta(\mathcal{B}^\circ)$ for $\beta < 0$ with $|\beta|$ small.

Sketch of the proof: step 1

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Variational characterisation

$$\lambda_1^\beta(\mathcal{M}) = \inf_{u \in H^1(\mathcal{M}) \setminus \{0\}} \frac{\|\nabla u\|_{L^2(\mathcal{M}; \mathbb{C}^2)}^2 + \beta \|u|_{\partial\mathcal{M}}\|_{L^2(\partial\mathcal{M})}^2}{\|u\|_{L^2(\mathcal{M})}^2}$$

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The ground-state $u_\circ(x) = \psi(\rho_{\partial \mathcal{B}^\circ}(x)) : \mathcal{B}^\circ \rightarrow \mathbb{R}$ of $H_{\beta, \mathcal{B}^\circ}$ is a radial function in geodesic polar coordinates on \mathcal{B}° .

$$u_\star(x) := \psi(\rho_{\partial \mathcal{M}}(x)) \in H^1(\mathcal{M}) \quad (\text{test function})$$

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$$\|u_\star|_{\partial \mathcal{M}}\|_{L^2(\partial \mathcal{M})} = \|u_\circ|_{\partial \mathcal{B}^\circ}\|_{L^2(\partial \mathcal{B}^\circ)} \quad (\text{trivial}).$$

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Sketch of the proof: step 2

$$\|u_\star\|_{L^2(\mathcal{M})} \leq \|u_o\|_{L^2(\mathcal{B}^\circ)} \text{ and } \|\nabla u_\star\|_{L^2(\mathcal{M};\mathbb{C}^2)} \leq \|\nabla u_o\|_{L^2(\mathcal{B}^\circ;\mathbb{C}^2)}$$

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An application to the Steklov-type eigenvalues

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$$\text{dom } D_{\lambda, \mathcal{M}} = \left\{ \varphi \in L^2(\partial \mathcal{M}) : \exists u \in H^1(\mathcal{M}) \text{ such that } -\Delta u = \lambda u \right. \\ \left. \text{with } u = \varphi \text{ on } \partial \mathcal{M} \text{ and } \partial_\nu u|_{\partial \mathcal{M}} \text{ exists in } L^2(\partial \mathcal{M}) \right\}.$$

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Proposition (Khalile-L-19)

$$\begin{cases} |\partial \mathcal{M}| = |\partial \mathcal{B}^\circ| \\ K_\circ \cdot \max\{|\mathcal{M}|, |\mathcal{B}^\circ|\} \leq 2\pi \end{cases} \implies \sigma_1^\lambda(\mathcal{M}) \leq \sigma_1^\lambda(\mathcal{B}^\circ), \quad \forall \lambda < 0.$$

- 1 Motivation & background
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The Robin Laplacian on $\Lambda_{\mathfrak{m}}$

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Main result

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An analogous result is known for δ -interactions on $\partial\Lambda_{\mathfrak{m}}$ (Exner-L-17).
The method of the proof used there is not applicable any more.

The strategy of the proof

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Variational characterisation

$$\lambda_1(\Lambda_m) = \inf_{u \in H^1(\Lambda_m) \setminus \{0\}} \frac{\|\nabla u\|_{L^2(\Lambda_m; \mathbb{C}^3)}^2 - \|u|_{\partial\Lambda_m}\|_{L^2(\partial\Lambda_m)}^2}{\|u\|_{L^2(\Lambda_m)}^2}$$

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The ground-state $u_o(x) = \psi\left(|x|, \rho_{\partial b}\left(\frac{x}{|x|}\right)\right) : \Lambda_b \rightarrow \mathbb{R}$ of H_{Λ_b} is rotationally invariant

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In the class of manifolds with the **Gauss curvature** bounded from above by $K_0 \geq 0$ and under the constraint of **fixed** perimeter, the **geodesic disk** of constant curvature K_0 maximizes the lowest Robin eigenvalue.

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The Laplacian on an unbounded three-dimensional Euclidean cone + an attractive Robin BC.

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Problem II: optimization on cones

The Laplacian on an unbounded three-dimensional Euclidean cone + an attractive Robin BC.

Under a constraint of fixed perimeter of the cross-section, the lowest Robin eigenvalue is maximized by the circular cone.

Thank you

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M. Khalile and V.L., Spectral isoperimetric inequalities for Robin Laplacians on 2-manifolds and unbounded cones, [arXiv:1909.10842](https://arxiv.org/abs/1909.10842).

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Thank you for your attention!